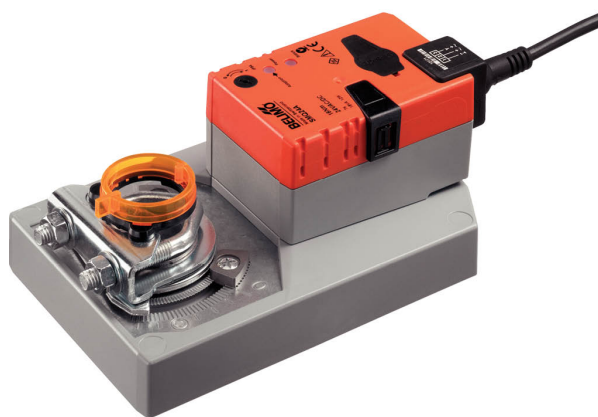


Configurable damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 3.2 m²
- Torque motor 16 Nm
- Nominal voltage AC/DC 24 V
- Control modulating 2...10 V variable
- Position feedback 2...10 V variable
- Running time motor 7 s variable



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.2...28.8 V / DC 21.6...28.8 V
	Power consumption in operation	15 W
	Power consumption in rest position	2 W
	Power consumption for wire sizing	26 VA
	Power consumption for wire sizing note	Imax 20 A @ 5 ms
	Connection supply / control	Cable 1 m, 4x 0.75 mm ²
	Parallel operation	Yes (note the performance data)
Functional data	Torque motor	16 Nm
	Torque variable	25%, 50%, 75% reduced
	Operating range Y	2...10 V
	Input impedance	100 kΩ
	Operating range Y variable	Start point 0.5...30 V End point 2.5...32 V
	Operating modes optional	Open/close Modulating (DC 0...32 V)
	Position feedback U	2...10 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.5...8 V End point 2.5...10 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)
	Direction of motion variable	electronically reversible
	Manual override	with push-button, can be locked
	Angle of rotation	Max. 95°
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops
Minimum angle of rotation	Min. 30°	
Running time motor	7 s / 90°	
Running time motor variable	7...35 s	
Adaptation setting range	manual (automatic on first power-up)	

Technical data

Functional data	Adaptation setting range variable	No action Adaptation when switched on Adaptation after pushing the manual override button	
	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%	
	Override control variable	MAX = (MIN + 32%)...100% MIN = 0%...(MAX - 32%) ZS = MIN...MAX	
	Sound power level, motor	63 dB(A)	
	Mechanical interface	Universal shaft clamp reversible 12...26.7 mm	
	Position indication	Mechanical, pluggable	
	Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
		Power source UL	Class 2 Supply
Degree of protection IEC/EN		IP54	
Degree of protection NEMA/UL		NEMA 2	
Enclosure		UL Enclosure Type 2	
EMC		CE according to 2014/30/EU	
Low voltage directive		CE according to 2006/95/EC	
Certification IEC/EN		IEC/EN 60730-1 and IEC/EN 60730-2-14	
UL Approval		cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
Hygiene test		According to VDI 6022 Part 1 / SWKI VA 104-01, cleanable and disinfectable, low emission	
Type of action		Type 1	
Rated impulse voltage supply / control		0.8 kV	
Pollution degree		3	
Ambient humidity		Max. 95% RH, non-condensing	
Ambient temperature		-30...40°C [-22...104°F]	
Ambient temperature note		Caution: 40...50°C utilisation possible only under certain restrictions. Please contact your supplier.	
Storage temperature	-40...80°C [-40...176°F]		
Servicing	maintenance-free		
Weight	Weight	1.7 kg	

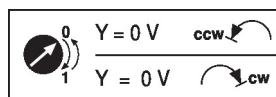
Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied with during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- Self adaptation is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaptation push-button once).
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section and the design, as well as the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

Product features

Operating mode	The actuator is connected with a standard control signal of 0...10 V and drives to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as control signal for other actuators.
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo service tools MFT-P or ZTH EU.
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti-rotation device to prevent the actuator from rotating.
Manual override	Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops. A minimum permissible angle of rotation of 30° must be allowed for.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	<p>The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out an adaptation, which is when the operating range and position feedback adjust themselves to the mechanical setting range.</p> <p>The detection of the mechanical end stops enables a gentle approach to the end positions, thus protecting the actuator mechanics.</p> <p>The actuator then moves into the position defined by the control signal.</p>
Adaptation and synchronisation	<p>An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC-Tool. Both mechanical end stops are detected during the adaptation (entire setting range). Automatic synchronisation after pressing the manual override button is configured. The synchronisation is in the home position (0%).</p> <p>The actuator then moves into the position defined by the control signal.</p> <p>A range of settings can be adapted using the PC-Tool (see MFT-P documentation)</p>



Accessories

Electrical accessories	Description	Type
	Auxiliary switch 1x SPDT add-on	S1A
	Auxiliary switch 2x SPDT add-on	S2A
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 10 kΩ add-on	P10000A
	Adapter for auxiliary switch and feedback potentiometer, Multipack 20 pcs.	Z-SPA
	Signal converter voltage/current 100 kΩ 4...20 mA, Supply AC/DC 24 V	Z-UIC
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
Mechanical accessories	Description	Type
	Actuator arm for standard shaft clamp	AH-GMA
	Ball joint suitable for damper crank arm KH8 / KH10	KG10A
	Damper crank arm Slot width 8.2 mm, clamping range ø14...25 mm	KH10
	Anti-rotation mechanism 230 mm, Multipack 20 pcs.	Z-ARS230
	Mounting kit for linkage operation for flat installation	ZG-GMA
	Position indicator, Multipack 20 pcs.	Z-PI
Tools	Description	Type
	Service tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
	* Adapter Z-SPA	
	It is imperative that this adapter will be ordered if an auxiliary switch or a feedback potentiometer is required and if at the same time the shaft clamp is installed on the rear side of the actuator (e.g. with short shaft installation).	

Electrical installation



Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

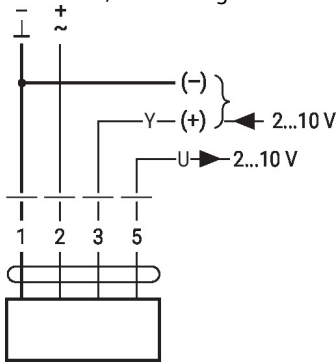
Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

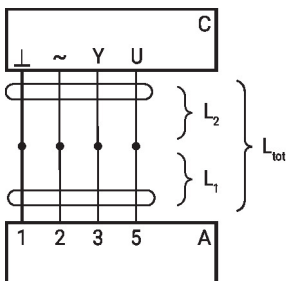
Electrical installation

Wiring diagrams

AC/DC 24 V, modulating



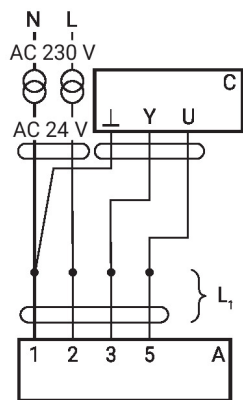
Signal cable lengths



L ₂	L _{tot} = L ₁ + L ₂	
	AC	DC
0.75 mm ²	≤30 m	≤5 m
1.00 mm ²	≤40 m	≤8 m
1.50 mm ²	≤70 m	≤12 m
2.50 mm ²	≤100 m	≤20 m

A = Actuator
 C = Control unit (controlling unit)
 L1 = Connecting cable of the actuator
 L2 = Customer cable
 Ltot = Maximum signal cable length

Note:
 When several actuators are connected in parallel, the maximum signal cable length must be divided by the number of actuators.



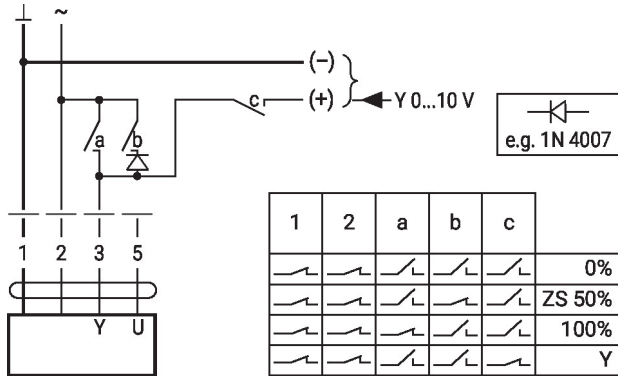
A = Actuator
 C = Control unit (controlling unit)
 L1 = Connecting cable of the actuator

Note:
 There are no special restrictions on installation if the supply and the data cable are routed separately.

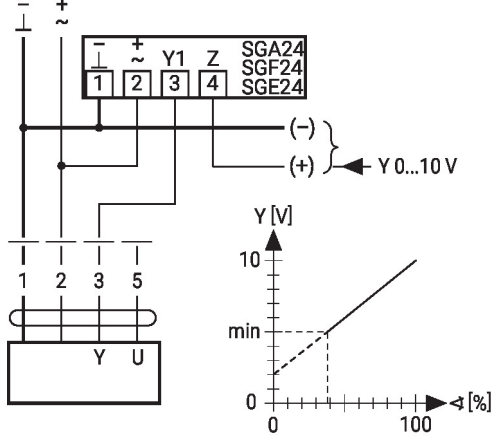
Functions

Functions with basic values (conventional mode)

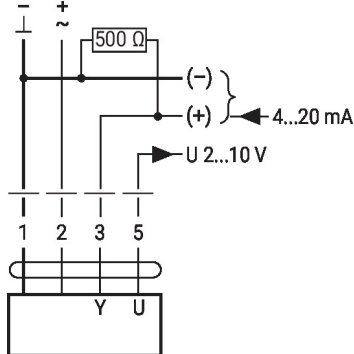
Override control with AC 24 V with relay contacts



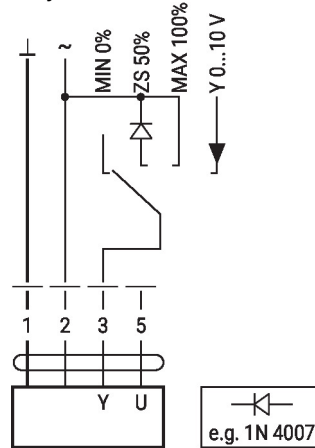
Minimum limit with positioner SG..



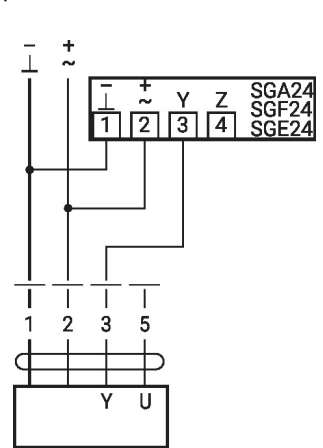
Control with 4...20 mA via external resistor



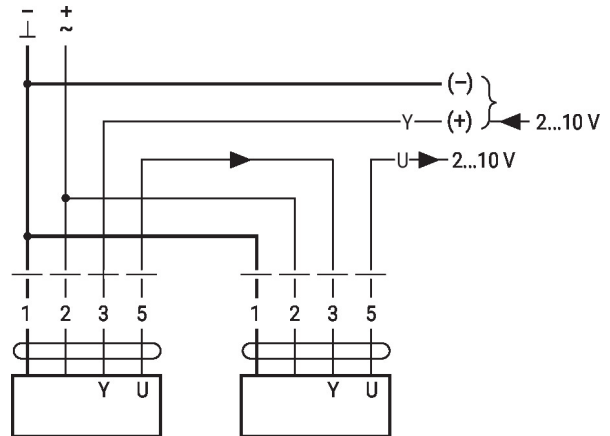
Override control with AC 24 V with rotary switch



Control remotely 0...100% with positioner SG..



Primary/secondary operation (position-dependent)



Caution:

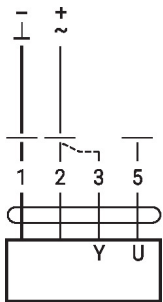
The operating range must be set to DC 2...10 V.

The 500 Ohm resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V.

Functions

Functions with basic values (conventional mode)

Functional check

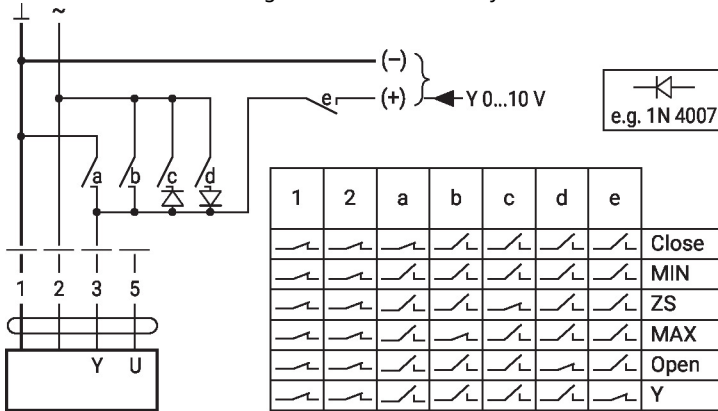


Procedure

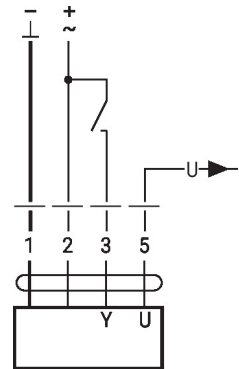
1. Connect 24 V to connections 1 and 2
2. Disconnect connection 3:
 - With direction of rotation 0: Actuator rotates to the left
 - With direction of rotation 1: Actuator rotates to the right
3. Short-circuit connections 2 and 3:
 - Actuator runs in opposite direction

Functions with specific parameters (Parametrisation necessary)

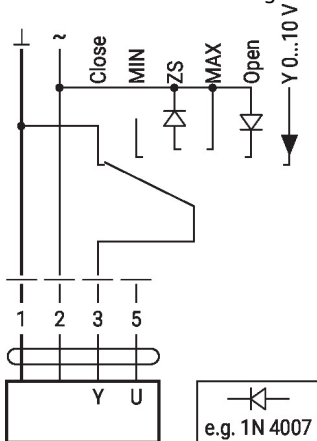
Override control and limiting with AC 24 V with relay contacts



Control open/close



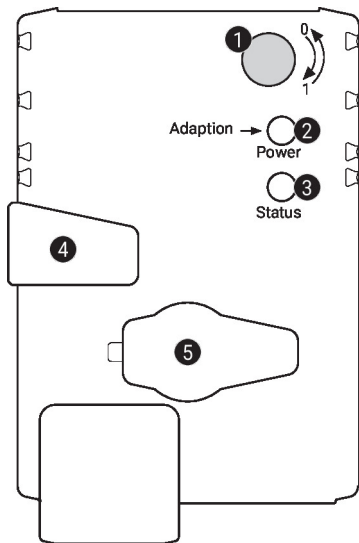
Override control and limiting with AC 24 V with rotary switch



Caution:

The "Close" function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

Operating controls and indicators


1 Direction of rotation switch

Switch over: Direction of rotation changes

2 Push-button and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

3 Push-button and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

Press button: No function

4 Manual override button

Press button: Gear train disengages, motor stops, manual override possible

Release button: Gear train engages, synchronisation starts, followed by standard mode

5 Service plug

For connecting parametrisation and service tools

Check power supply connection

2 Off and **3** On Possible wiring error in power supply

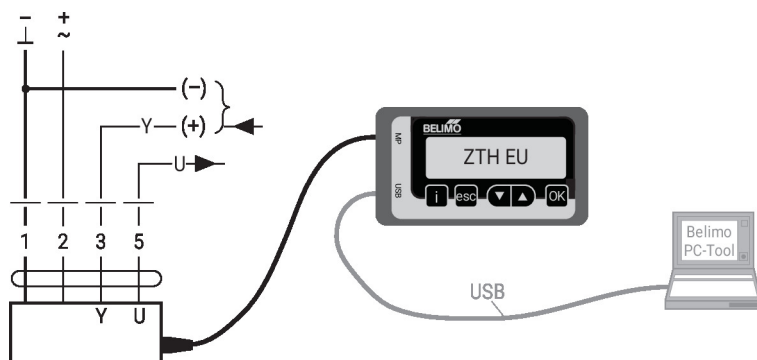
Installation notes

Negative torque Max. 50% of the torque (Caution: Application possible only with restrictions. Please contact your supplier.)

Service

Tool connection The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



Dimensions

Spindle length

	Min. 52
	Min. 20

Clamping range

	12...22	12...18
	22...26.7	12...18

*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.

